Brandon Benanti

Algorithm:

Set robot speed to 55

Roll straight for 1.7 seconds

Stop

Delay for 1 second

Set speed to 59

Turn right and roll for 1.97 seconds

Stop

Delay for 1 second

Set speed to 55

Turn left and roll for 2.18 seconds

Stop

Delay for 1 second

Set speed to 150

Turn right and roll for 1.97 seconds

Stop

Delay for 2 seconds

Turn right and roll for 3 seconds

Stop

End program